

# Superfluid Brillouin optomechanics

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## SI A OMIT/OMIA measurements

### SI A.1 Theory

In this section we describe the theory of Optomechanically Induced Transparency and Optomechanically Induced Amplification (OMIT/OMIA) measurements when a slow photothermal process exists in addition to the usual optomechanical coupling. Using the same notation as the main paper, the standard optomechanics Hamiltonian is

$$\hat{\mathcal{H}} = \hbar\omega_\alpha \hat{a}_\alpha^\dagger \hat{a}_\alpha + \hbar\omega_\beta \hat{b}_\beta^\dagger \hat{b}_\beta + \hbar g_0^{\alpha,\beta} (\hat{b}_\beta + \hat{b}_\beta^\dagger) \hat{a}_\alpha^\dagger \hat{a}_\alpha + \hbar\sqrt{\kappa_{\alpha,\text{in}}} (s_{\text{in}}^* \hat{a}_\alpha + s_{\text{in}} \hat{a}_\alpha^\dagger) \quad (1)$$

where  $\kappa_{\alpha,\text{in}}$  is the input coupling and  $s_{\text{in}}$  is the amplitude of the incoming laser beam

$$s_{\text{in}} = (\bar{s}_{\text{in}} + \delta s_{\text{in}}(t)) e^{-i\omega_{\text{L}} t} \quad (2)$$

Here  $\bar{s}_{\text{in}}$  is a strong “control” beam and  $\delta s_{\text{in}}(t)$  is a weak “probe” beam.

The Heisenberg equations of motion are

$$\dot{\hat{a}}_\alpha = -i(\omega_\alpha \hat{a}_\alpha + g_0^{\alpha,\beta} (\hat{b}_\beta + \hat{b}_\beta^\dagger) \hat{a}_\alpha + \sqrt{\kappa_{\alpha,\text{in}}} s_{\text{in}}) - \frac{\kappa_\alpha}{2} \hat{a}_\alpha \quad (3)$$

and:

$$\dot{\hat{b}}_\beta = -i(\omega_\beta \hat{b}_\beta + g_0^{\alpha,\beta} \hat{a}_\alpha^\dagger \hat{a}_\alpha) - \frac{\gamma_\beta}{2} \hat{b}_\beta - i g_T \delta T \quad (4)$$

with the damping rates  $\kappa_\alpha$  and  $\gamma_\beta$  for the cavity field and the acoustic mode correspondingly. Since OMIT/OMIA is a coherent measurement, the thermal noise of the acoustic mode (which is incoherent) can be neglected. The last term in equation 4 describes the driving of the acoustic mode by changes in the helium temperature  $\delta T$ . The acoustic mode is coupled to the temperature fluctuations with the coupling rate  $g_T$  which has units of Hz/K. Furthermore, we assume that  $\delta T$  undergoes simple relaxation towards an equilibrium value set by the intracavity photon number.

$$\dot{\delta T} = g_{\text{ta}} \hat{a}_\alpha^\dagger \hat{a}_\alpha - \kappa_{\text{th}} \delta T \quad (5)$$

In this equation  $g_{\text{ta}}$  is the single photon heating rate in units of K/s, and  $\kappa_{\text{th}}$  is the relaxation rate of the temperature of the helium inside the cavity.

The two beams produce intensity beating with frequency  $\Omega_D \approx \omega_\beta$  and with amplitude  $A$ , so

$$\hat{a}_\alpha^\dagger \hat{a}_\alpha = \bar{n}_\alpha + (Ae^{-i\Omega_D t} + \text{c.c.}) \quad (6)$$

Here  $\bar{n}_\alpha$  is the average circulating photon number. We combine equation 6 with equation 5 and solve for  $\delta T$ , ignoring the constant temperature shift (due to  $\bar{n}_\alpha$ ). The solution is

$$\delta T = \frac{g_{\text{ta}}}{\kappa_{\text{th}}} \left( \frac{Ae^{-i\Omega_D t}}{1 - i\Omega_D/\kappa_{\text{th}}} + \text{c.c.} \right) \quad (7)$$

Plugging this back into equation 4 and ignoring the counter-rotating term proportional to  $e^{+i\Omega_D t}$  gives

$$\dot{\hat{b}}_\beta = -i \left( \omega_\beta \hat{b}_\beta + g_0^{\alpha,\beta} \bar{n}_\alpha + \left( g_0^{\alpha,\beta} + g_T \frac{g_{\text{ta}}}{\kappa_{\text{th}}} \frac{1}{1 - i\Omega_D/\kappa_{\text{th}}} \right) Ae^{-i\Omega_D t} \right) - \frac{\gamma_\beta}{2} \hat{b}_\beta \quad (8)$$

We now define

$$g_{0,\text{pt}}^{\alpha,\beta} = g_T \frac{g_{\text{ta}}}{\kappa_{\text{th}}} \frac{1}{i + \Omega_D/\kappa_{\text{th}}} \approx g_T \frac{g_{\text{ta}}}{\Omega_D} \approx g_T \frac{g_{\text{ta}}}{\omega_\beta}, \quad (9)$$

where we've assumed that the thermal relaxation rate  $\kappa_{\text{th}}$  is much smaller than the drive frequency  $\Omega_D$ . The total coupling to the beat note part of the intracavity power is  $g_{\text{tot}} = g_0^{\alpha,\beta} (1 + ig_{0,\text{pt}}^{\alpha,\beta}/g_0^{\alpha,\beta}) = g_0^{\alpha,\beta} G$ , where  $G$  is defined as

$$G = 1 + i \frac{g_{0,\text{pt}}^{\alpha,\beta}}{g_0^{\alpha,\beta}} \quad (10)$$

With this modification, equation 4 becomes

$$\dot{\hat{b}}_\beta = -i(\omega_\beta \hat{b}_\beta + g_0^{\alpha,\beta} \bar{n}_\alpha + g_0^{\alpha,\beta} G A e^{-i\Omega_D t}) - \frac{\gamma_\beta}{2} \hat{b}_\beta \quad (11)$$

Note that the equation of motion for  $\hat{a}_\alpha$  (equation 3) is not influenced by the inclusion of this photothermal process, because the action of the acoustic mode on the intracavity light is only via changes in the He density, which are fully parameterized by  $\hat{b}_\beta$ .

In the frame rotating at  $\omega_L$ , defining  $\Delta = \omega_L - \omega_\alpha$ , and redefining  $\hat{a}_\alpha$  and  $s_{\text{in}}$  to be rotating at  $\omega_L$  as well, we have

$$\dot{\hat{a}}_\alpha = i\Delta \hat{a}_\alpha - ig_0^{\alpha,\beta} (\hat{b}_\beta + \hat{b}_\beta^\dagger) \hat{a}_\alpha - i\sqrt{\kappa_{\alpha,\text{in}}} s_{\text{in}} - \frac{\kappa_\alpha}{2} \hat{a}_\alpha \quad (12)$$

The steady state equations are

$$\bar{a}_\alpha = \frac{-i\sqrt{\kappa_{\alpha,\text{in}}} \bar{s}_{\text{in}}}{-i\bar{\Delta} + \frac{\kappa_\alpha}{2}} \quad (13)$$

and

$$\bar{b}_\beta = \frac{-ig_0^{\alpha,\beta} |\bar{a}_\alpha|^2}{i\omega_\beta + \frac{\gamma_\beta}{2}} \quad (14)$$

where an effective detuning is defined:  $\bar{\Delta} = \Delta - g_0^{\alpha,\beta} (\bar{b}_\beta + \bar{b}_\beta^*)$ .

Now we linearize the equations around the mean optical amplitude  $\bar{a}$ , mean acoustic amplitude  $\bar{b}$  and average laser drive  $\bar{s}_{\text{in}}$ , by assuming  $\hat{a}_\alpha(t) = \bar{a}_\alpha + \delta\hat{a}_\alpha(t)$ ,  $\hat{b}_\beta(t) = \bar{b}_\beta + \delta\hat{b}_\beta(t)$  and  $s_{\text{in}} = \bar{s}_{\text{in}} + \delta s_{\text{in}}(t)$ . Plugging this assumption into equations 12 and 4 and making use of equations 13 and 14 we have

$$\delta\dot{\hat{a}}_\alpha(t) = i\bar{\Delta}\delta\hat{a}_\alpha(t) - ig_0^{\alpha,\beta}(\delta\hat{b}_\beta(t) + \delta\hat{b}_\beta^\dagger(t))\bar{a}_\alpha - i\sqrt{\kappa_{\alpha,\text{in}}}\delta s_{\text{in}}(t) - \frac{\kappa_\alpha}{2}\delta\hat{a}_\alpha(t) \quad (15)$$

$$\delta\dot{\hat{b}}_\beta(t) = -i\omega_\beta\delta\hat{b}_\beta(t) - ig_0^{\alpha,\beta}G(\bar{a}^*\delta\hat{a}_\alpha(t) + \bar{a}\delta\hat{a}_\alpha^\dagger(t)) - \frac{\gamma_\beta}{2}\delta\hat{b}_\beta \quad (16)$$

In the equation 16 we recognized that  $\bar{a}^*\delta\hat{a}_\alpha(t) + \bar{a}\delta\hat{a}_\alpha^\dagger(t)$  is the term corresponding to the intracavity power beat note that we've denoted as  $(Ae^{-i\Omega_D t} + \text{c.c.})$  earlier, so its optomechanical coupling should have the photothermal correction factor  $G$ . The Fourier transform of equation 15 is

$$-i\omega\delta\hat{a}_\alpha[\omega] = i\bar{\Delta}\delta\hat{a}_\alpha[\omega] - ig_0^{\alpha,\beta}(\delta\hat{b}_\beta[\omega] + \delta\hat{b}_\beta^\dagger[\omega])\bar{a}_\alpha - i\sqrt{\kappa_{\alpha,\text{in}}}\delta s_{\text{in}}[\omega] - \frac{\kappa_\alpha}{2}\delta\hat{a}_\alpha[\omega] \quad (17)$$

By defining the cavity susceptibility

$$\chi_{\text{cav}}[\omega] = \frac{1}{-i\omega - i\bar{\Delta} + \frac{\kappa_\alpha}{2}} \quad (18)$$

and multiphoton coupling

$$g = g_0^{\alpha,\beta}\bar{a}_\alpha \quad (19)$$

we can rewrite equation 17 and its complex conjugate as

$$\delta\hat{a}_\alpha[\omega] = -i\chi_{\text{cav}}[\omega] \left( g(\delta\hat{b}_\beta[\omega] + \delta\hat{b}_\beta^\dagger[\omega]) + \sqrt{\kappa_{\alpha,\text{in}}}\delta s_{\text{in}}[\omega] \right) \quad (20)$$

$$\delta\hat{a}_\alpha^\dagger[\omega] = i\chi_{\text{cav}}^*[-\omega] \left( g^*(\delta\hat{b}_\beta[\omega] + \delta\hat{b}_\beta^\dagger[\omega]) + \sqrt{\kappa_{\alpha,\text{in}}}\delta s_{\text{in}}^*[\omega] \right) \quad (21)$$

Now we take the Fourier transform of equation 16

$$-i\omega\delta\hat{b}_\beta[\omega] = -i\omega_\beta\delta\hat{b}_\beta[\omega] - iG(g^*\delta\hat{a}_\alpha[\omega] + g\delta\hat{a}_\alpha^\dagger[\omega]) - \frac{\gamma_\beta}{2}\delta\hat{b}_\beta[\omega] \quad (22)$$

Combining equations 20 and 21

$$(g^*\delta\hat{a}_\alpha[\omega] + g\delta\hat{a}_\alpha^\dagger[\omega]) = i|g|^2(\delta\hat{b}_\beta[\omega] + \delta\hat{b}_\beta^\dagger[\omega])(\chi_{\text{cav}}^*[-\omega] - \chi_{\text{cav}}[\omega]) + i\sqrt{\kappa_{\alpha,\text{in}}}(\chi_{\text{cav}}^*[-\omega]\delta s_{\text{in}}^*[\omega]g - \chi_{\text{cav}}[\omega]\delta s_{\text{in}}[\omega]g^*) \quad (23)$$

Since  $\gamma_\beta \ll \omega_\beta$ , we can neglect the counter-rotating term  $\delta\hat{b}_\beta^\dagger[\omega]$ , which is peaked around  $-\omega_\beta$ , so

$$\delta\hat{b}_\beta[\omega] = \frac{G\sqrt{\kappa_{\alpha,\text{in}}}(\chi_{\text{cav}}^*[-\omega]\delta s_{\text{in}}^*[\omega]g - \chi_{\text{cav}}[\omega]\delta s_{\text{in}}[\omega]g^*)}{-i(\omega - \omega_\beta) + \frac{\gamma_\beta}{2} + G|g|^2(\chi_{\text{cav}}[\omega] - \chi_{\text{cav}}^*[-\omega])} \quad (24)$$

Defining

$$i\Sigma[\omega] = G|g|^2(\chi_{\text{cav}}[\omega] - \chi_{\text{cav}}^*[-\omega]) \quad (25)$$

results in

$$\delta \hat{b}_\beta[\omega] = \frac{G\sqrt{\kappa_{\alpha,\text{in}}}(\chi_{\text{cav}}^*[-\omega]\delta s_{\text{in}}^*[\omega]g - \chi_{\text{cav}}[\omega]\delta s_{\text{in}}[\omega]g^*)}{-i(\omega - \omega_\beta) + \frac{\gamma_\beta}{2} + i\Sigma[\omega]} \quad (26)$$

In this notation the optical spring  $\Delta\omega_{\beta(\text{opt})}$  and optical damping  $\gamma_{\beta(\text{opt})}$  are correspondingly

$$\Delta\omega_{\beta(\text{opt})} = \text{Re}[\Sigma[\omega]] \quad (27)$$

$$\gamma_{\beta(\text{opt})} = -2\text{Im}[\Sigma[\omega]] \quad (28)$$

Now we calculate the amplitude and phase of the OMIA signal. In order to observe OMIT/OMIA it is necessary to have two beams detuned by a frequency nearly equal to that of the acoustic oscillator. As shown by equation 2, there are two beams in the system: a strong control beam and a weak probe beam. The probe beam is detuned from the control beam by  $-\Omega$ , where  $\Omega > 0$ . In the rotating frame, the expression for  $\delta s_{\text{in}}(t)$  is

$$\delta s_{\text{in}}(t) = s_p e^{i\Omega t} \quad (29)$$

Taking the Fourier transform and assuming  $s_p$  to be real

$$\delta s_{\text{in}}[\omega] = \sqrt{2\pi}s_p\delta(\omega + \Omega) \quad (30)$$

Putting this back into equation 24

$$\delta \hat{b}_\beta[\omega] = \frac{\sqrt{2\pi}s_p G\sqrt{\kappa_{\alpha,\text{in}}}(g\chi_{\text{cav}}^*[-\omega]\delta(\omega - \Omega) - g^*\chi_{\text{cav}}[\omega]\delta(\omega + \Omega))}{-i(\omega - \omega_\beta) + \frac{\gamma_\beta}{2} + i\Sigma[\omega]} \quad (31)$$

Going back into the time domain

$$\delta \hat{b}_\beta(t) = b_+[\Omega]s_p e^{-i\Omega t} + b_-[\Omega]s_p e^{i\Omega t} \quad (32)$$

where

$$b_+[\Omega] = \frac{G\sqrt{\kappa_{\alpha,\text{in}}}\chi_{\text{cav}}^*[-\Omega]g}{-i(\Omega - \omega_\beta) + \frac{\gamma_\beta}{2} + i\Sigma[\Omega]} \quad (33)$$

and

$$b_-[\Omega] = \frac{G\sqrt{\kappa_{\alpha,\text{in}}}(-\chi_{\text{cav}}[-\Omega]g^*)}{-i(-\Omega - \omega_\beta) + \frac{\gamma_\beta}{2} + i\Sigma[-\Omega]} \quad (34)$$

The expression for  $b_+$  gives the complex amplitude of the acoustic oscillator. Oscillating at  $-\Omega$ ,  $b_-$  is far off resonance, so it will be small.

The optical amplitude is given by equation 20 as

$$\delta \hat{a}_\alpha[\omega] = -i\chi_{\text{cav}}[\omega] \left( g(\delta \hat{b}_\beta[\omega] + \delta \hat{b}_\beta^\dagger[\omega]) + \sqrt{\kappa_{\alpha,\text{in}}}\delta s_{\text{in}}[\omega] \right) \quad (35)$$

Recasting the acoustic mode amplitude in the time domain and neglecting  $b_-$  yields

$$g(\delta \hat{b}_\beta(t) + \delta \hat{b}_\beta^\dagger(t)) + \sqrt{\kappa_{\alpha,\text{in}}}\delta s_{\text{in}}(t) = (gb_+[\Omega]e^{-i\Omega t} + (gb_+^*[\Omega] + \sqrt{\kappa_{\alpha,\text{in}}})e^{i\Omega t})s_p \quad (36)$$

We express the cavity mode amplitude as

$$\delta \hat{a}_\alpha(t) = a_+[\Omega]e^{-i\Omega t} + a_-[\Omega]e^{i\Omega t} \quad (37)$$

where

$$a_+[\Omega] = -i\chi_{\text{cav}}[\Omega]gb_+[\Omega]s_p \quad (38)$$

and

$$a_-[\Omega] = -i\chi_{\text{cav}}[-\Omega] \left( gb_+^*[\Omega] + \sqrt{\kappa_{\alpha,\text{in}}} s_p \right) \quad (39)$$

In the measurement scheme employed in the experiment (having a probe beam only at  $-\Omega$ ) only  $a_-$  can be measured. In figure 2 of the main paper, we plot  $a_-$  normalized with respect to the background. This normalized signal  $a'_-$  is given by:

$$a'_-[\Omega] = \frac{a_-[\Omega]}{a_-[\infty]} = \frac{gb_+^*[\Omega]}{\sqrt{\kappa_{\alpha,\text{in}}}} + 1 \quad (40)$$

The functions  $a[\Omega]$  and  $\psi[\Omega]$  are the magnitude and phase of  $a'_-[\Omega]$ . The values  $A$  and  $\Psi$ , described in the main paper are found as follows

$$A = \text{abs} \left[ \frac{gb_+^*[\omega_\beta]}{\sqrt{\kappa_{\alpha,\text{in}}}} \right] \quad (41)$$

$$\Psi = \arg \left[ \frac{gb_+^*[\omega_\beta]}{\sqrt{\kappa_{\alpha,\text{in}}}} \right] \quad (42)$$

Where  $b_+^*[-\omega_\beta]$  is the complex amplitude of the acoustic oscillator, when the the probe beam is detuned by  $-\omega_\beta$  from the control beam.

## SI A.2 Full treatment of phase modulation.

In order to use the treatment above to describe the measurements discussed in the main text, we need to take into account some additional features of the measurement setup.

First, as mentioned in the main text, the probe and the control beams are generated in a phase modulator. Specifically, two microwave tones drive the phase modulator: a stronger one at frequency  $\omega_{\text{control}}$ , and a weaker one at  $\omega_{\text{probe}} = \omega_{\text{control}} + \Omega$  (in the actual experiment we also send a third, even weaker, tone that is used for locking the laser to the cavity; its power is at least 3 times lower than the probe tone and it is at a different frequency, so it has a negligible effect on the measurement result). The strong and the weak microwave tones generate the control and the probe optical tones respectively, while the optical carrier acts as a local oscillator in the heterodyne measurement. However, phase modulation generates sidebands symmetrically about the carrier, resulting in negative-order sidebands on the other side of the carrier. These are far enough detuned from the cavity that they don't noticeably affect the mechanical motion; nevertheless, their beat notes with the carrier are phase-coherent with the beat notes produced by the control and probe beams, so they will partially cancel the expected heterodyne signal, thus influencing the measurement result.

Moreover, in some of the measurements the microwave tones are strong enough that we need to take into account higher-order optical sidebands (e.g., at frequencies  $2\omega_{\text{control}}$  or  $\omega_{\text{control}} + \omega_{\text{probe}}$ ). These can contribute to the beat note in the photocurrent, and can also be close enough to the cavity resonance to influence mechanical motion.

Finally, the local oscillator is not infinitely far detuned from the cavity (in our case, it is detuned by  $\sim 15\kappa$ ). Hence, it experiences some cavity-induced phase shift in reflection, which also needs to be taken into account.

In order to consistently account for all the factors listed above, we start with the description of the phase modulator. We denote the incident optical tone by  $a_0 e^{-i\omega_0 t}$ , and a set of microwave tones by  $\phi_n \cos(\omega_n t)$ , where the  $\phi_n$  are the microwave amplitudes normalized by the (possibly frequency-dependent)  $V_\pi$  of the phase modulator, and the  $\omega_n$  are the corresponding microwave frequencies. The output of the modulator is then expressed as

$$a_\phi = a_0 e^{-i\omega_0 t} e^{i \sum_n \phi_n \cos(\omega_n t)} = a_0 e^{-i\omega_0 t} \prod_n e^{i\phi_n \cos(\omega_n t)} \quad (43)$$

Next, we use the Jacobi-Anger expansion for the exponents

$$e^{i\phi_n \cos(\omega_n t)} = \sum_{k=-\infty}^{+\infty} (-i)^k J_k(\phi_n) e^{-ik\omega_n t}, \quad (44)$$

where  $J_k(z)$  is  $k^{\text{th}}$  Bessel function of the first kind. With this, the output laser becomes

$$a_\phi = a_0 e^{-i\omega_0 t} \prod_n \left[ \sum_{k=-\infty}^{+\infty} (-i)^k J_k(\phi_n) e^{-ik\omega_n t} \right] \equiv e^{-i\omega_0 t} \sum_l a_l e^{-i\omega_l t}, \quad (45)$$

where  $\omega_l$  are all possible intermodulation frequencies resulting from the  $\omega_n$ . In practice, to keep the computation time short we limit our calculations to a finite intermodulation order (as discussed below).

Next, we consider all of these beams (including the carrier) landing on the cavity. To recap equations 12 and 11, the equations of motion can be written as

$$\dot{a}_\alpha = -(\kappa_\alpha/2 + i\omega_\alpha) a_\alpha - i g_0^{\alpha,\beta} a_\alpha (b_\beta + b_\beta^*) - i\sqrt{\kappa_{\alpha,\text{in}}} s_{\text{in}} \quad (46)$$

$$\dot{b}_\beta = -(\gamma_\beta/2 + i\omega_\beta) b_\beta - i g_0^{\alpha,\beta} G a_\alpha^* a_\alpha \quad (47)$$

In the frame rotating at the carrier frequency  $\omega_0$  the incident optical field becomes  $s_{\text{in}} = \sum_l a_l e^{-i\omega_l t}$ , and the optical equation of motion can be written as

$$\dot{a}_\alpha = -(\kappa_\alpha/2 - i\Delta) a_\alpha - i g_0^{\alpha,\beta} a_\alpha (b_\beta + b_\beta^*) - i\sqrt{\kappa_{\alpha,\text{in}}} \sum_l a_l e^{-i\omega_l t}, \quad (48)$$

with  $\Delta = \omega_0 - \omega_\alpha$  being the carrier (i.e., local oscillator) detuning.

As usual, next we linearize this equation. To zeroth order in  $g_0^{\alpha,\beta}$ , the field amplitude is

$$a_0 = \sum_l a_{l,0} e^{-i\omega_l t} \quad (49)$$

$$a_{l,0} = -i\sqrt{\kappa_{\alpha,\text{in}}} a_l \chi_{\text{cav}}[\omega_l], \quad (50)$$

where  $\chi_{\text{cav}}[\omega] = (\kappa_\alpha/2 - i(\omega + \Delta))^{-1}$ . This amplitude results in a force on the mechanical oscillator given by

$$F_0 = -i g_0^{\alpha,\beta} G a_0^* a_0 = -i g_0^{\alpha,\beta} G \sum_l \sum_k a_{l,0} a_{k,0}^* e^{-i(\omega_l - \omega_k)t} \quad (51)$$

The first order in  $g_0^{\alpha,\beta}$  terms due to the mechanical motion are (in the adiabatic regime, where  $\gamma_\beta \ll \kappa_\alpha$ )

$$a_1 = -ig_0^{\alpha,\beta} \sum_l a_{l,0} e^{-i\omega_l t} (b_\beta \chi_{\text{cav}}[\omega_l + \omega_\beta] + b_\beta^* \chi_{\text{cav}}[\omega_l - \omega_\beta]) \quad (52)$$

Their contribution to the mechanical force is

$$\begin{aligned} F_1 &= -ig_0^{\alpha,\beta} G(a_0^* a_1 + a_0 a_1^*) \\ &= (g_0^{\alpha,\beta})^2 G \sum_l \sum_k a_{l,0} a_{k,0}^* e^{-i(\omega_l - \omega_k)t} [b_\beta (\chi_{\text{cav}}^*[\omega_k - \omega_\beta] - \chi_{\text{cav}}[\omega_l + \omega_\beta]) \\ &\quad + b_\beta^* (\chi_{\text{cav}}^*[\omega_k + \omega_\beta] - \chi_{\text{cav}}[\omega_l - \omega_\beta])] \end{aligned} \quad (53)$$

We can make a couple of simplifying assumptions. First, we note that  $b_\beta$  rotates at  $+\omega_\beta$ , while  $b_\beta^*$  is located around  $-\omega_\beta$ . This means that they will be coupled only by the terms rotating at  $2\omega_\beta$  (i.e., for  $|\omega_k - \omega_l| \approx 2\omega_\beta$ ). In our case, these terms should be very small, since they would only come from the higher (at least, fourth) order in sideband amplitudes. Thus, we can neglect the  $b_\beta^*$  term and get

$$F_1 = -i\Sigma b_\beta \quad (54)$$

$$\Sigma = i(g_0^{\alpha,\beta})^2 G \sum_l \sum_k a_{l,0} a_{k,0}^* e^{-i(\omega_l - \omega_k)t} (\chi_{\text{cav}}^*[\omega_k - \omega_\beta] - \chi_{\text{cav}}[\omega_l + \omega_\beta]) \quad (55)$$

Second, we are predominantly interested in the DC terms in  $\Sigma$ ; everything else will result in terms rotating at frequencies other than  $\omega_\beta$  and, again, will end up far away from the acoustic resonance. As a result, the acoustic equation of motion becomes

$$\dot{b}_\beta = -(\gamma_\beta/2 + i\omega_\beta + i\Sigma)b_\beta + F_0 \quad (56)$$

$$\Sigma = i(g_0^{\alpha,\beta})^2 G \sum_l |a_{l,0}|^2 (\chi_{\text{cav}}^*[\omega_l - \omega_\beta] - \chi_{\text{cav}}[\omega_l + \omega_\beta]) \quad (57)$$

The solution for this equation is

$$b_\beta = -i(g_0^{\alpha,\beta})^2 G \sum_l \sum_k \chi_{\beta,\text{eff}}[\omega_l - \omega_k] a_{l,0} a_{k,0}^* e^{-i(\omega_l - \omega_k)t} \quad (58)$$

$$\chi_{\beta,\text{eff}}[\omega] = (\gamma_\beta/2 + i\omega_\beta + i\Sigma - i\omega)^{-1} \quad (59)$$

Finally, knowing this expression for  $b_\beta$  we can obtain the intracavity power using the first-order solution (equation (52)). Some of the terms in  $a_1$  will end up being phase-coherent with the initial optical drive (e.g., the motional sideband on the control beam will be phase-coherent with the probe beam, and vice versa). It is these terms that will define the OMIT response.

For the analysis presented in the main body of the paper, we implement this procedure as follows

- First, knowing the microwave drives and phase modulator response, calculate the tones on the output of the phase modulator using equation 45 (for practical reasons, we limit expansion to the third order in the control beam amplitude and to the first order in the probe beam amplitude);
- Next, from equations 49 and 50 determine the zeroth order intracavity field;

- Use this to calculate the optical force (equation 51) and self-energy (equation 57);
- From these, determine the mechanical response (equations 58 and 59);
- Use this calculated response to get the resulting field inside the cavity  $a_\alpha = a_0 + a_1$ , where  $a_1$  is determined by equation 52
- The reflected field is found using the standard input-output relations  $a_{\alpha,\text{out}} = a_{\alpha,\text{in}} - i\sqrt{\kappa_{\alpha,\text{in}}}a_\alpha$ ;
- Finally, to relate this field to the measurable quantities, we calculate the electrical response of the photodiode  $I \propto a_{\alpha,\text{out}}^* a_{\alpha,\text{out}}$ , which will consist of all possible beat notes of the reflected optical tones. The amplitude of the electrical tone oscillating at  $\omega_{\text{probe}}$  (which mainly comes of the beating of the probe beam with the carrier) is the relevant OMIT signal.

All of these calculation are performed numerically.

## SI B Optical and acoustic transmission of the cavity mirrors

### SI B.1 General considerations

A cavity made of two lossless mirrors with power transmittances  $T_1$  and  $T_2$  has finesse [1]

$$\mathcal{F} = \frac{2\pi}{T_1 + T_2} \quad (60)$$

The corresponding quality factor is

$$Q = \frac{f}{\gamma} = \mathcal{F} \frac{f}{FSR} = \frac{\mathcal{F}f(2L)}{v} = \frac{4\pi fL}{v(T_1 + T_2)} \quad (61)$$

Here  $f$  and  $\gamma$  are the frequency and linewidth of the cavity mode,  $L$  is the cavity length and  $v$  is the speed of wave propagation (either optical or acoustic). A conventional way of creating mirrors with very low loss and low transmission is by using Distributed Bragg Reflectors (DBRs).

### SI B.2 The optical transmission through a DBR

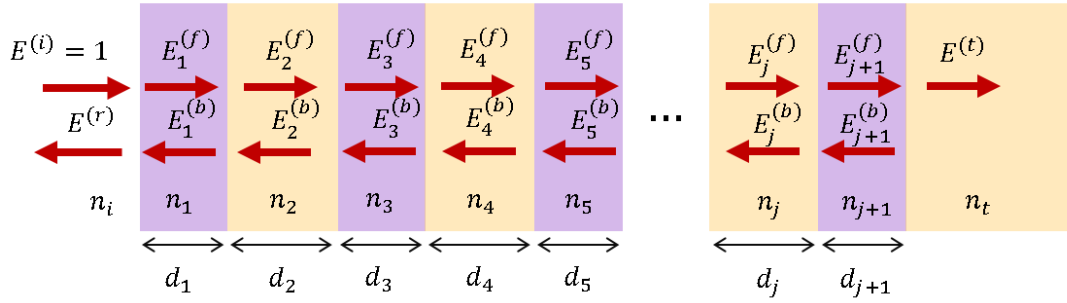
This brief review follows the treatment in ref.[2]. Figure 1 shows a schematic representation of a DBR, where the amplitude of the incident field is  $E^{(i)} = 1$ , the amplitudes of reflected and transmitted fields are  $E^{(r)}$  and  $E^{(t)}$  correspondingly and the amplitude of the fields propagating forward and backward in the  $j^{\text{th}}$  layer are  $E_j^{(f)}$  and  $E_j^{(b)}$  correspondingly. The index of refraction of the material from which the wave is incident is  $n_i$  and the index of refraction of the material into which the wave is transmitted is  $n_t$ . The index of refraction of the  $j^{\text{th}}$  layer is  $n_j$  and the thickness of the  $j^{\text{th}}$  layer is  $d_j$ . The  $x$ -axis is pointing to the right.

Assume a plane wave approaches the DBR at normal incidence. The continuity of parallel components of electric and magnetic fields at each interface results in the following boundary conditions

$$E_j(x, t) = E_{j+1}(x, t) \quad (62)$$

$$\frac{dE_j(x, t)}{dx} = \frac{dE_{j+1}(x, t)}{dx} \quad (63)$$





**Figure 1:** DBR showing the electric field in each layer. Color indicates different materials.

At the first interface, the boundary conditions give

$$1 + E^{(r)} = E_1^{(f)} + E_1^{(b)} \quad (64)$$

$$n_i (1 - E^{(r)}) = n_1 (E_1^{(f)} - E_1^{(b)}) \quad (65)$$

Applying the boundary conditions to the interface between the  $j^{\text{th}}$  and  $(j+1)^{\text{th}}$  layers yields the equations

$$E_j^{(f)} e^{ikn_j d_j} + E_j^{(b)} e^{-ikn_j d_j} = E_{j+1}^{(f)} + E_{j+1}^{(b)} \quad (66)$$

$$n_j (E_j^{(f)} e^{ikn_j d_j} - E_j^{(b)} e^{-ikn_j d_j}) = n_{j+1} (E_{j+1}^{(f)} - E_{j+1}^{(b)}) \quad (67)$$

Assuming the total number of layers is  $p$ , applying boundary conditions to the last interface yields

$$E_p^{(f)} e^{ikn_p d_p} + E_p^{(b)} e^{-ikn_p d_p} = E^{(t)} \quad (68)$$

$$n_p (E_p^{(f)} e^{ikn_p d_p} - E_p^{(b)} e^{-ikn_p d_p}) = n_t E^{(t)} \quad (69)$$

Expressing the equations 64-69 in matrix form

$$\begin{bmatrix} 1 & 1 \\ n_i & -n_i \end{bmatrix} \begin{bmatrix} 1 \\ E^{(r)} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ n_1 & -n_1 \end{bmatrix} \begin{bmatrix} E_1^{(f)} \\ E_1^{(b)} \end{bmatrix} \quad (70)$$

$$\begin{bmatrix} e^{ikn_j d_j} & e^{-ikn_j d_j} \\ n_j e^{ikn_j d_j} & -n_j e^{-ikn_j d_j} \end{bmatrix} \begin{bmatrix} E_j^{(f)} \\ E_j^{(b)} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ n_{j+1} & -n_{j+1} \end{bmatrix} \begin{bmatrix} E_{j+1}^{(f)} \\ E_{j+1}^{(b)} \end{bmatrix} \quad (71)$$

$$\begin{bmatrix} e^{ikn_p d_p} & e^{-ikn_p d_p} \\ n_p e^{ikn_p d_p} & -n_p e^{-ikn_p d_p} \end{bmatrix} \begin{bmatrix} E_p^{(f)} \\ E_p^{(b)} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ n_t & 0 \end{bmatrix} \begin{bmatrix} E^{(t)} \\ 0 \end{bmatrix} \quad (72)$$

Upon rearranging and combining equations 70-72 we arrive at

$$\begin{bmatrix} 1 \\ E^{(r)} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ n_i & -n_i \end{bmatrix}^{-1} \prod_{j=1}^p M_j \begin{bmatrix} 1 & 0 \\ n_t & 0 \end{bmatrix} \begin{bmatrix} E^{(t)} \\ 0 \end{bmatrix} \quad (73)$$

where  $M_j$  is defined as

$$M_j = \begin{bmatrix} 1 & 1 \\ n_j & -n_j \end{bmatrix} \begin{bmatrix} e^{ikn_j d_j} & e^{-ikn_j d_j} \\ n_j e^{ikn_j d_j} & -n_j e^{-ikn_j d_j} \end{bmatrix}^{-1} \quad (74)$$

We define:

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ n_i & -n_i \end{bmatrix}^{-1} \prod_{j=1}^p M_j \begin{bmatrix} 1 & 0 \\ n_t & 0 \end{bmatrix} \quad (75)$$

and now we have

$$\begin{bmatrix} 1 \\ E^{(r)} \end{bmatrix} = A \begin{bmatrix} E^{(t)} \\ 0 \end{bmatrix} \quad (76)$$

from which we find

$$r_{\text{opt}} = E^{(r)} = a_{21}/a_{11} \quad (77)$$

$$T_{\text{opt}} = 1 - r_{\text{opt}}^2 \quad (78)$$

To conclude, finding the transmittivity of the DBR involves calculating the matrix  $A$ , which is straightforward, provided we know the indexes of refraction  $n_i$  and  $n_t$ , and the structure of the DBR, which is fully described by  $n$  and  $d$  of the alternating DBR layers.

### SI B.3 The acoustic transmission through a DBR

Finding the DBR transmittivity for the sound wave is done in a similar manner [3, 4]. Assume a sound wave with frequency  $f$  and wavelength  $\lambda$  is incident on a DBR. Equating the displacements ( $s(x, t)$ ) and pressures ( $P(x, t) = -K ds/dx$ ) on both sides of the boundary ( $K$  is the bulk modulus) gives

$$s_j(d, t) = s_{j+1}(d, t) \quad (79)$$

$$K_j \frac{ds_j}{dx}(d, t) = K_{j+1} \frac{ds_{j+1}}{dx}(d, t) \quad (80)$$

The fact that acoustic impedance is related to bulk modulus via  $Z = K/v = v\rho$ , where  $\rho$  is the density of the material, and that the frequency of the mode must be constant throughout the DBR, results in three sets of equations that provide information about the amplitude of the acoustic mode at different interfaces. At the first interface

$$1 + s^{(r)} = s_1^{(f)} + s_1^{(b)} \quad (81)$$

$$Z_i(1 - s^{(r)}) = Z_1(s_1^{(f)} - s_1^{(b)}) \quad (82)$$

At the interface between the  $j^{\text{th}}$  and  $(j+1)^{\text{th}}$  layer:

$$s_j^{(f)} e^{ikn_j^{\text{ac}} d_j} + s_j^{(b)} e^{-ikn_j^{\text{ac}} d_j} = s_{j+1}^{(f)} + s_{j+1}^{(b)} \quad (83)$$

$$Z_j(s_j^{(f)} e^{ikn_j^{\text{ac}} d_j} - s_j^{(b)} e^{-ikn_j^{\text{ac}} d_j}) = Z_{j+1}(s_{j+1}^{(f)} - s_{j+1}^{(b)}) \quad (84)$$

Here we defined  $k = 2\pi/\lambda$  and  $n_j^{\text{ac}} = v_i/v_j$ , where  $v_i$  and  $v_j$  are correspondingly the speed of the sound wave in the medium on the incident side and the speed of sound in the  $j^{\text{th}}$  layer. At the last interface, assuming a total number of layers  $p$

$$s_p^{(\text{f})} e^{ikn_p^{\text{ac}} d_p} + s_p^{(\text{b})} e^{-ikn_p^{\text{ac}} d_p} = s^{(\text{t})} \quad (85)$$

$$Z_p \left( s_p^{(\text{f})} e^{ikn_p^{\text{ac}} d_p} - s_p^{(\text{b})} e^{-ikn_p^{\text{ac}} d_p} \right) = Z_t s^{(\text{t})} \quad (86)$$

From equations 81-86, using the same methods as in section SI B.2, a matrix  $B$  is obtained:

$$B = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ Z_i & -Z_i \end{bmatrix}^{-1} \prod_{j=1}^p M_j^{\text{ac}} \begin{bmatrix} 1 & 0 \\ Z_t & 0 \end{bmatrix} \quad (87)$$

where  $M_j^{\text{ac}}$  is defined as:

$$M_j^{\text{ac}} = \begin{bmatrix} 1 & 1 \\ Z_j & -Z_j \end{bmatrix} \begin{bmatrix} e^{ikn_j^{\text{ac}} d_j} & e^{-ikn_j^{\text{ac}} d_j} \\ Z_j e^{ikn_j^{\text{ac}} d_j} & -Z_j e^{-ikn_j^{\text{ac}} d_j} \end{bmatrix}^{-1} \quad (88)$$

Now we have:

$$\begin{bmatrix} 1 \\ s^{(\text{r})} \end{bmatrix} = B \begin{bmatrix} s^{(\text{t})} \\ 0 \end{bmatrix} \quad (89)$$

from which we get:

$$r_{\text{ac}} = s^{(\text{r})} = b_{21}/b_{11} \quad (90)$$

$$T_{\text{ac}} = 1 - r_{\text{ac}}^2 \quad (91)$$

In conclusion, to calculate both optical and acoustic reflection/transmission of a DBR the following quantities need to be known:

- $d$  - thickness of each layer
- $n_{\text{opt}}$  - optical index of refraction for each layer
- $\rho$  - density for each layer
- $v$  - sound velocity in each layer

Additionally, it is necessary to know the values of those parameters for the material from which the wave is incident and the material into which the wave is transmitted. For the experiments described in the main paper these are liquid  $^4\text{He}$  and  $\text{SiO}_2$  respectively.

#### SI B.4 Optical and acoustic quality factors for the present DBRs

The DBRs in these experiments are deposited on to the faces of  $\text{SiO}_2$  fibers. The DBR is comprised of alternating layers of  $\text{SiO}_2$  and  $\text{Ta}_2\text{O}_5$  whose thicknesses are chosen to correspond to one-quarter wavelength of the light (which in vacuum has wavelength  $\sim 1550$  nm). The cavity is formed between two such fibers immersed in superfluid helium; therefore we are interested in the transmission of light and sound from the superfluid helium, through the DBR, and into the fiber.

Material	$n_{opt}$	$v(\text{m/s})$	$\rho (\text{kg/m}^3)$
$^4\text{He}$	1.0282[5]	238[5]	145[5]
$\text{SiO}_2$	1.4746[6]	$5,900 \pm 100$ [7, 8]	2,200[7]
$\text{Ta}_2\text{O}_5$	2.0483[6]	$4,500 \pm 500$ [7]	$7,600 \pm 600$ [7]

**Supplementary Table 1:** Material properties of superfluid  $^4\text{He}$ ,  $\text{SiO}_2$  and  $\text{Ta}_2\text{O}_5$

Table 1 shows the relevant parameters for each material.

For the 1550 nm light, a quarter optical wavelength layer of  $\text{SiO}_2$  is 263 nm and a quarter optical wavelength layer of  $\text{Ta}_2\text{O}_5$  is 189 nm. The 1550 nm light has wavelength equal to 1508 nm in liquid  $^4\text{He}$  and therefore couples to the acoustic mode with 754 nm wavelength in liquid  $^4\text{He}$ , whose frequency is 315.7 MHz. For this mode, a quarter acoustic wavelength in  $\text{SiO}_2$  is  $4.7 \pm 0.1 \mu\text{m}$  and a quarter acoustic wavelength in  $\text{Ta}_2\text{O}_5$  is  $3.6 \pm 0.4 \mu\text{m}$ ; the large discrepancy between the optical and acoustic wavelengths *in the solid materials* means that the DBRs used in the present device will not provide strong reflectivity for the acoustic waves.

The experiment was performed with the mirror surfaces separated by  $84 \mu\text{m}$ . The cavity consisted of a low reflectivity (15 layer pairs) input DBR and high reflectivity (18 layer pairs) back DBR. The laser wavelength was 1538 nm; the frequency of the acoustic mode of interest was  $\omega_\beta = 2\pi \times 317.3 \text{ MHz}$ .

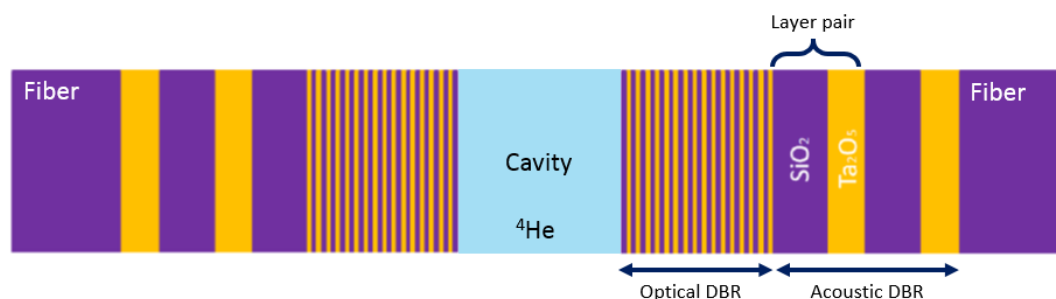
As mentioned above, the DBRs in the present devices are not designed to be highly reflective for the acoustic waves; nevertheless, the strong contrast in acoustic impedance between  $^4\text{He}$  and the outermost layer of the optical DBR provides fairly large reflectivity. From equation 91 the acoustic transmittivity for the low reflectivity DBR is calculated to be  $10,100 \pm 400 \text{ ppm}$ , while the acoustic transmittivity for the high reflectivity DBR is calculated to be  $7,700 \pm 1,300 \text{ ppm}$ . The uncertainties predominantly come from the material properties of  $\text{Ta}_2\text{O}_5$  (see Table 1). These values of the acoustic transmission lead to the acoustic quality factor  $Q_{\beta,\text{ext}} = 79,000 \pm 5,000$  which is slightly higher than the experimentally determined quality factor  $Q_{\beta,\text{ext}} = 70,000 \pm 2,000$ . This difference might be attributed to various factors, such as losses due to mirror misalignment or imprecise knowledge of the DBR structure.

## SI B.5 Improving the acoustic quality factor in future devices

In this section we consider the possibility of improving the acoustic quality factor by adding an acoustic DBR between the substrate and the optical DBR. The proposed structure is shown in figure 2.

We consider a cavity in which optical confinement is again provided by optical DBRs with 15 and 18 pairs, optimized for maximum reflectivity at 1550 nm, and the acoustic confinement is enhanced by additional layers forming an acoustic DBR. Technical aspects of the coating process impose the requirement that the total stack thickness be less than  $25 \mu\text{m}$ , and that the thickness of each layer of a given material is an integer multiple of the thickness of the thinnest layer of this material[6]. Maximizing  $Q_{\beta,\text{ext}}$  for the 315.7 MHz acoustic mode (to which 1550 nm light couples), subject to the above constraints, we find the optimal design for the stack. Table 2 shows stack parameters for the current designs as well as the proposed designs.

We use equations 78 and 91 to calculate the optical and acoustic transmission for the DBRs presented in table 2. The results are shown in table 3. The optical transmission doesn't change appreciably as more



**Figure 2:** Example of a DBR structure that would be reflective for both optical and acoustic waves

Number	Design
1 (Current)	Substrate $\times$ (189 nm $\text{Ta}_2\text{O}_5 \times 253$ nm $\text{SiO}_2$ ) <sup>15</sup> $\times$ 189 nm $\text{Ta}_2\text{O}_5$
2 (Current)	Substrate $\times$ (189 nm $\text{Ta}_2\text{O}_5 \times 253$ nm $\text{SiO}_2$ ) <sup>18</sup> $\times$ 189 nm $\text{Ta}_2\text{O}_5$
3 (Future )	Substrate $\times$ 3591 nm $\text{Ta}_2\text{O}_5 \times 4554$ nm $\text{SiO}_2 \times 3591$ nm $\text{Ta}_2\text{O}_5 \times 759$ nm $\text{SiO}_2 \times$ (189 nm $\text{Ta}_2\text{O}_5 \times 253$ nm $\text{SiO}_2$ ) <sup>15</sup> $\times$ 189 nm $\text{Ta}_2\text{O}_5$
4 (Future )	Substrate $\times$ 3780 nm $\text{Ta}_2\text{O}_5 \times 4554$ nm $\text{SiO}_2 \times 3213$ nm $\text{Ta}_2\text{O}_5 \times$ (253 nm $\text{SiO}_2 \times 189$ nm $\text{Ta}_2\text{O}_5$ ) <sup>18</sup>

**Supplementary Table 2:** The stack designs used in the current device and the future stack designs

acoustic layers are added, as the acoustic layers are outside of the optical mode. At the same time, the acoustic layers decrease the acoustic transmission by more than an order of magnitude. Assuming the

Number	$T_{\text{opt}}$ (ppm)	$T_{\text{ac}}$ (ppm)	$d_{\text{total}}$ ( $\mu\text{m}$ )	$\frac{U^{\text{SiO}_2}}{U^{\text{He}}} \text{ (ppm)}$	$\frac{U^{\text{Ta}_2\text{O}_5}}{U^{\text{He}}} \text{ (ppm)}$	$Q_{\beta, \text{loss}}$
1	73.5	$10,000 \pm 400$	6.6	$6.5 \pm 0.5$	$17.1 \pm 2.1$	$4.2 \times 10^7$
2	10.2	$8,100 \pm 1200$	8.3	$6.4 \pm 0.9$	$16.8 \pm 1.5$	$4.3 \times 10^7$
3	73.5	$350 \pm 200$	19.68	$3.8 \pm 1$	$9.5 \pm 2$	$7.5 \times 10^7$
4	10.2	$420 \pm 240$	19.87	$3.1 \pm 1$	$7.8 \pm 1.4$	$9.2 \times 10^7$

**Supplementary Table 3:** The calculated parameters for different stacks. The optical transmittivity ( $T_{\text{opt}}$ ), acoustic transmittivity ( $T_{\text{ac}}$ ) and thickness ( $d_{\text{total}}$ ) are discussed in section SI B.5. The ratios of the energy stored in  $\text{SiO}_2$  ( $U^{\text{SiO}_2}/U^{\text{He}}$ ) and  $\text{Ta}_2\text{O}_5$  ( $U^{\text{Ta}_2\text{O}_5}/U^{\text{He}}$ ) to the energy stored in Helium are discussed in SI B.6

mirror separation is  $84 \mu\text{m}$  (as in the present devices), we calculate the expected acoustic quality factor to be  $Q_{\beta, \text{ext}} = 3.3 \pm 2.2 \times 10^6$ , where the uncertainty is primarily due to the acoustic parameters of  $\text{Ta}_2\text{O}_5$ . This calculation assumes a cavity constructed from Device #3 and Device #4 in Tables 2 and 3.

## SI B.6 Acoustic loss inside the DBR layers

In addition to being limited by the transmission of the acoustic mode into the fiber, the acoustic Q factor can also be limited by dissipation in the DBR. To estimate the Q factor associated with this loss, the following expression is used

$$\frac{1}{Q_{\beta, \text{loss}}} = \frac{U^{\text{SiO}_2} \phi_{\text{SiO}_2} + U^{\text{Ta}_2\text{O}_5} \phi_{\text{Ta}_2\text{O}_5}}{U^{\text{He}}} \quad (92)$$

Here  $U$  is the energy stored in the material;  $\phi$  is the acoustic loss angle for the material.

To find the stored energy, we use the treatment above to find the displacement field in each layer. The stored energy can then be expressed as

$$\begin{aligned} U_j^{\text{stored}} &\propto \int_0^{d_j} \omega_{\beta}^2 \rho_j |s_j^{(f)} e^{ikn_j^{\text{ac}} x} + s_j^{(b)} e^{-ikn_j^{\text{ac}} x}|^2 dx \\ &= \omega_{\beta}^2 \rho_j \left[ (|s_j^{(f)}|^2 + |s_j^{(b)}|^2) d_j - \frac{1}{kn_j^{\text{ac}}} \text{Im} \left( s_j^{(f)*} s_j^{(b)} (e^{-2ikn_j^{\text{ac}} d_j} - 1) \right) \right] \end{aligned} \quad (93)$$

The calculated ratios of energy stored in  $\text{SiO}_2$  and  $\text{Ta}_2\text{O}_5$  are shown in table 3. Both  $\phi_{\text{SiO}_2}$  and  $\phi_{\text{Ta}_2\text{O}_5}$  have been measured over a range of temperatures and for frequencies mostly much lower than 300 MHz [9, 10, 11, 12, 13, 14, 15, 16]. All of these measurements show  $\phi_{\text{SiO}_2}, \phi_{\text{Ta}_2\text{O}_5} < 10^{-3}$ . The values of the quality factor due to absorption in the DBR ( $Q_{\beta, \text{loss}}$ ), assuming  $\phi_{\text{SiO}_2} = \phi_{\text{Ta}_2\text{O}_5} = 10^{-3}$ , are shown in Table 3. For all designs  $Q_{\beta, \text{loss}}$  is much larger than  $Q_{\beta, \text{ext}}$ . As a result, the acoustic quality factor should not be limited by the acoustic absorption in the DBR.

## SI C Acoustic loss in the superfluid helium.

### SI C.1 Intrinsic temperature dependent loss

For  $T < 600$  mK the main intrinsic loss mechanism for density waves (i.e., first sound) in superfluid helium is the three phonon process [17]. It can be described by an amplitude attenuation coefficient  $\alpha_{3pp}$

$$\alpha_{3pp}(\omega_{\beta}) = \frac{\pi^2 (u+1)^2 k_B^4}{30 \rho_{He} \hbar^3 v_{He}^6} \omega_{\beta} T^4 \left( \arctan(\omega_{\beta} \tau) - \arctan \left( \frac{3}{2} \gamma \bar{p}^2 \omega_{\beta} \tau \right) \right) \quad (94)$$

Here  $\omega_{\beta}$  is the wave frequency,  $T$  is the temperature,  $\rho_{He} = 145 \text{ kg/m}^3$  and  $v_{He} = 238 \text{ m/s}$  are the helium density and sound velocity,  $u = 2.84$  is the Grüneisen constant [18],  $\tau = \xi T^{-5}$  is the thermal phonon lifetime, where  $\xi = 1.11 \times 10^{-7} \text{ s} \cdot \text{K}^5$  [19] and  $\bar{p} = 3k_B T / v_{He}$  is the average thermal phonon momentum. Finally,  $\gamma$  is the coefficient for the cubic term in the phonon dispersion, which is expressed as  $\gamma = -\frac{1}{6v_{He}} \frac{d^3 \epsilon}{dp^3}$ , where  $\epsilon$  and  $p$  are phonon energy and momentum respectively. It has been measured to be  $\gamma = -8 \times 10^{47} \text{ kg}^{-2} \text{ m}^{-2} \text{ s}^2$  [18].

The intrinsic quality factor of an acoustic mode can be calculated from the attenuation length as

$$Q_{\beta, \text{int}} = \frac{\omega_{\beta}}{2v_{He} \alpha_{3pp}} \quad (95)$$

For the relevant acoustic mode frequency  $\omega_\beta = 2\pi \times 313.86$  MHz and temperature  $T < 0.5$  K both arctan arguments in equation 94 are  $\gg 1$ , leading to the simple relationship

$$Q_{\beta,\text{int}} = \frac{\chi}{T^4}, \quad (96)$$

where  $\chi \approx 118 \text{ K}^4$ .

## SI C.2 Heat transport model and thermal response time.

In order to make use of the equations 94 and 95 to analyze the data in the main paper, it is necessary to know the temperature of the helium inside the cavity. To accomplish this, we have developed a model of heat transport in the device. The steady state solution of this model yields the dependence of the device temperature on the dissipated power and the temperature of the mixing chamber, and is used to derive equation 2 in the main text. The dynamical solution provides an expression for the thermal relaxation time of the helium inside the cavity.

### Heat transport equation

First, let us define the geometry of the device. As shown in figure 1a of the main text, a cylindrical volume of helium occupies the space between the faces of two optical fibers which are confined within the bore of a glass ferrule. The helium inside the cavity is thermally linked to a larger volume of helium outside the ferrule via two identical sheaths; since these sheaths have the same length, we can represent them as a single sheath with doubled cross-sectional area. Finally, we assume that the helium outside the ferrule has large heat capacitance and a good thermal link to the mixing chamber, so its temperature doesn't depend on the power dissipated inside the cavity and is the same as the mixing chamber temperature.

We represent the helium inside the cavity as a point heat capacitance  $C_0(T)$  located at  $x = l$  and experiencing a heat load  $\Phi$  (dissipated laser power). This capacitance is connected to a reservoir at  $x = 0$  through a one-dimensional channel (the combined sheaths), which has a heat capacitance per unit length  $C_l(T)$  and a thermal resistance per unit length  $R_l(T)$ . The reservoir is maintained at a constant temperature  $T_{\text{MC}}$ . If we denote the temperature dependent specific heat (per unit volume) of helium by  $c_V(T)$  and its thermal conductivity in the channel by  $\kappa(T)$ , we get for the parameters above

$$C_0(T) = V_{\text{cav}} c_V(T) \quad (97)$$

$$C_l(T) = A_{\text{sh}} c_V(T) \quad (98)$$

$$R_l(T) = (A_{\text{sh}} \kappa(T))^{-1}, \quad (99)$$

where  $V_{\text{cav}}$  is the volume of the cylindrical cavity and  $A_{\text{sh}}$  is the combined cross-sectional area of the sheaths.

The two equations governing the heat transport in the channel are

$$j = -\frac{1}{R_l(T)} \frac{\partial T}{\partial x} \quad (100)$$

$$C_l(T) \frac{\partial T}{\partial t} = -\frac{\partial j}{\partial x} \quad (101)$$

The first equation relates the heat current  $j(x)$  and the temperature gradient  $\frac{\partial T}{\partial x}$  (positive values of  $j$  denote the heat flowing in the positive  $x$  direction, i.e., from the reservoir into the cavity), and the second one describes the heating of the helium inside the channel. The boundary condition at the reservoir is simply  $T(x = 0) = T_{MC}$ , while for the cavity it is expressed through a heat flow balance

$$\Phi = \left( C_0 \frac{\partial T}{\partial t} - j \right) \Big|_{x=l} \quad (102)$$

This last relation shows that the power  $\Phi$  dissipated in the cavity is partially spent on increasing its temperature and partially transmitted into the channel.

Because the thermal conductivity  $\kappa$  and heat capacity  $c$  are temperature-dependent, the equations above are in principle non-linear. Nevertheless, since they have the same dependence  $c(T) = \delta_V T^3$ ,  $\kappa(T) = \epsilon_V T^3$ , we can transform the equations into linear ones with an appropriate substitution. For that, we express the material parameters as

$$C_l(T) = A_{sh} c(T) = \delta_l T^3 \quad (103)$$

$$C_0(T) = V_{cav} c(T) = \delta_0 T^3 \quad (104)$$

$$R_l(T) = (A_{sh} \kappa(T))^{-1} = (\epsilon_l T^3)^{-1}, \quad (105)$$

where  $\delta_l = A_{sh} \delta_V$ ,  $\delta_0 = V_{cav} \delta_V$  and  $\epsilon_l = A_{sh} \epsilon_V$ . Substituting these expressions into the equation and boundary conditions, we obtain

$$j(x) = -\epsilon_l T^3 \frac{\partial T}{\partial x} = -\frac{\epsilon_l}{4} \frac{\partial(T^4)}{\partial x} \quad (106)$$

$$-\frac{\partial j}{\partial x} = \delta_l T^3 \frac{\partial T}{\partial t} = \frac{\delta_l}{4} \frac{\partial(T^4)}{\partial t} \quad (107)$$

$$\Phi = \left( \delta_0 T^3 \frac{\partial T}{\partial t} - j \right) \Big|_{x=l} = \left( \frac{\delta_0}{4} \frac{\partial(T^4)}{\partial t} - j \right) \Big|_{x=l} \quad (108)$$

Denoting  $u = T^4$  and using the first equation to express  $j$  leads to

$$\frac{\partial u}{\partial t} = \frac{\epsilon_l}{\delta_l} \frac{\partial^2 u}{\partial x^2} \quad (109)$$

$$u|_{x=0} = u_0 \quad (110)$$

$$\left( \frac{\partial u}{\partial t} + \frac{\epsilon_l}{\delta_0} \frac{\partial u}{\partial x} \right) \Big|_{x=l} = \frac{4\Phi}{\delta_0} \quad (111)$$

Thus, the heat transport equation is expressed as a one-dimensional diffusion equation with the diffusion coefficient  $D = \epsilon_l / \delta_l$ .

### Steady state solution

First, we consider a steady state solution with a constant heat load  $\Phi$ . The diffusion equation turns into  $\frac{\partial^2 u}{\partial x^2} = 0$ , which has a general solution  $u = a + bx$ . The boundary condition at  $x = 0$  immediately



yields  $a = u_0 = T_{\text{MC}}^4$ . From the second boundary condition we find  $b = \frac{\partial u}{\partial x} = \frac{4\Phi}{\epsilon_l}$ , which results in

$$u(x) = u_0 + \frac{4\Phi}{\epsilon_l}x, \quad (112)$$

From this, the temperature of the cavity can be determined as

$$T_{\text{cav}}^4 = u(l) = T_{\text{MC}}^4 + \frac{4\Phi}{\epsilon_l}l \quad (113)$$

This relation is used to derive equation 2 in the main text.

### Transient dynamics

Next, we consider the dynamics of this system. We consider the system in the steady state derived above and then abruptly turn off the power source at  $t = 0$ . The cavity temperature should then decay to  $T_0$  exponentially with some characteristic time  $\tau_0$ , which we want to determine.

To find the time evolution we use the eigenfunctions expansion of the solution:

$$u(x, t) = u_0 + \sum_n T_n(t)v_n(x), \quad (114)$$

where  $v_n(x)$  is an eigenfunction of the Laplace operator with the appropriate boundary conditions

$$\frac{\partial^2 v_n}{\partial x^2} = -\lambda_n v_n \quad (115)$$

$$v_n(0) = 0 \quad (116)$$

$$\left( \frac{\epsilon_l}{\delta_l} \frac{\partial^2 v_n}{\partial x^2} + \frac{\epsilon_l}{\delta_0} \frac{\partial v_n}{\partial x} \right) \Big|_{x=l} = 0 \quad (117)$$

If we denote  $\lambda_n = k_n^2$  (choosing the opposite sign  $\lambda = -k_n^2$  results in the inability to satisfy both boundary conditions simultaneously, as well as an exponentially diverging time evolution), we get from the first two equations that  $v_n(x) = \sin(k_n x)$ . The boundary condition at  $x = l$  restricts the values of  $k_n$

$$-\frac{\epsilon_l}{\delta_l} k_n^2 \sin(k_n l) + \frac{\epsilon_l}{\delta_0} k_n \cos(k_n l) = 0, \quad (118)$$

which can be rewritten as

$$(k_n l) \tan(k_n l) = r_V \quad (119)$$

with  $r_V = \frac{l\delta_l}{\delta_0} = \frac{lA_{sh}}{V_{cav}} = \frac{V_{sh}}{V_{cav}}$  is the ratio of the sheath and the cavity volumes. The solutions for this equation exhaust all of the values  $k_n$ .

Now we can substitute the expansion back into equation 109 to obtain the equations for the time-dependent parts  $T_n$ :

$$\frac{\partial u}{\partial t} = \frac{\epsilon_l}{\delta_l} \frac{\partial^2 u}{\partial x^2} \quad (120)$$

$$\sum_n v_n \frac{\partial T_n}{\partial t} = \frac{\epsilon_l}{\delta_l} \sum_n T_n \frac{\partial^2 v_n}{\partial x^2} = -\frac{\epsilon_l}{\delta_l} \sum_n k_n^2 T_n v_n \quad (121)$$

As the eigenfunctions are orthogonal, equation 121 has to be satisfied for each  $T_n$  independently

$$\frac{\partial T_n}{\partial t} = -\frac{\epsilon_l k_n^2}{\delta_l} T_n = -\frac{T_n}{\tau_n}, \quad (122)$$

where  $\tau_n = \frac{\delta_l}{\epsilon_l k_n^2}$  is the characteristic decay time. The solution for this equation is

$$T_n(t) = T_n(0)e^{-t/\tau_n}, \quad (123)$$

We're mostly interested in the longest relaxation time  $\tau_0$  corresponding to the smallest value of  $k_n$ , which we denote as  $k_0$

$$\tau_0 = \frac{\delta_l}{\epsilon_l} \frac{1}{k_0^2} \quad (124)$$

With several percent error,  $k_0$  can be approximated by

$$(k_0 l)^{-2} \approx \left(\frac{2}{\pi}\right)^2 + r_V, \quad (125)$$

so the relaxation time becomes

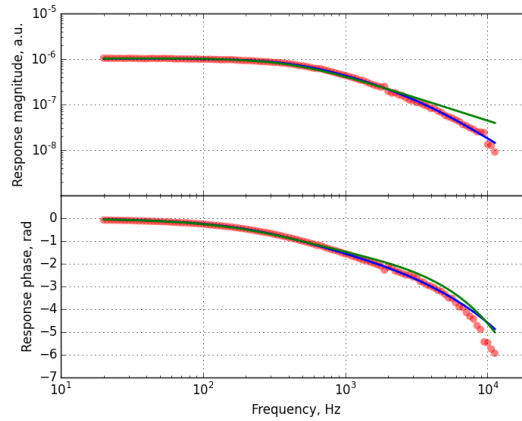
$$\tau_0 \approx \frac{\epsilon_l}{\delta_l} l^2 \left(\frac{4}{\pi^2} + r_V\right) = \frac{\delta_l T^3 l}{\epsilon_l T^3 / l} \left(\frac{4}{\pi^2} + r_V\right) = \frac{cl^2}{\kappa} \left(\frac{4}{\pi^2} + r_V\right) = \frac{C_{\text{sh}}}{K_{\text{sh}}} \left(\frac{4}{\pi^2} + r_V\right), \quad (126)$$

where  $C_{\text{sh}} = cA_{\text{sh}}l = \delta_l T^3 l$  is the total heat capacitance of the sheath, and  $K_{\text{sh}} = \kappa A_{\text{sh}}/l = \epsilon_l T^3 / l$  is the total thermal conductance of the sheath.

The expression above for the thermal relaxation time  $\tau_0$  depends only the sheath's heat capacitance, thermal conductance, and the geometric parameter  $r_V$ . The heat capacitance of the sheath can be known fairly well, since it only depends on its volume and the specific heat of the liquid helium, which for low temperatures is well known [20]. Thermal conductivity, however, is much harder to evaluate *a priori*, since it depends upon the particular geometry of the conducting channel (which determines the mean phonon travel length between collisions with the boundaries) and the scattering properties of its wall. Therefore, measurements of  $\tau_0$  can provide an estimate for the thermal conductivity without the need for any assumptions about the specularity of reflections from sheath surface.

## Measurement of the thermal relaxation time

We measure  $\tau_0$  by changing the circulating optical power (which is proportional to the power dissipated inside the cavity) and monitoring the response of the temperature-dependent linewidth of the acoustic mode. The experiment is performed using the OMIT/OMIA technique described in the main text, but with the probe beam frequency  $\omega_{\text{probe}}$  being fixed exactly one acoustic frequency away from the control beam:  $\omega_{\text{probe}} = \omega_{\text{control}} + \omega_{\beta}$ . This way, the magnitude of the OMIA part of the probe beam reflection is inversely proportional to the linewidth of the acoustic mode, which is a monotonic function of the device temperature. Hence, by observing the OMIA response as a function of time we can access the temperature dynamics. In practice, rather than measuring a step response to a change in the dissipated



**Figure 3:** Amplitude and phase of the intrinsic linewidth response as a function of the modulation frequency of the circulating optical power. The blue line is the fit to a double exponential (127); for comparison, the green line shows the fit to a simple exponential decay with a time delay, which corresponds to setting  $\tau_1 = 0$  in the equation 127.

optical power, we perform a lock-in measurement where we sinusoidally modulate the optical drive and record the complex response of the magnitude of the OMIA signal.

The results are shown in figure 3. The data was fit to a double exponential decay with two time scales  $\tau_s$  and  $\tau_f$  and an additional time delay  $\tau_d$

$$\delta\gamma_{int}[\omega] \propto \frac{1}{1 + i\omega\tau_s} \frac{1}{1 + i\omega\tau_f} e^{i\omega\tau_d} \quad (127)$$

We attribute the longer of the two decay times  $\tau_s \approx 350 \mu\text{s}$  to the thermal response. The shorter time  $\tau_f \approx 40 \mu\text{s}$  is only required to account for the data at frequencies above 2 kHz; it might arise from some other faster thermal process in the system (e.g., heating of the dielectric stack, or thermal equilibration of the helium inside the cavity), or from the time-delayed mechanical response itself. Finally, the time delay  $\tau_d \approx 30 \mu\text{s}$  can be attributed to the sound propagation delay, as it is comparable to the ballistic phonon travel time in the sheath  $l/v_{He} \approx 12 \mu\text{s}$ . In interpreting the slowest time  $\tau_s$  as the thermal response time  $\tau_0$  we assumed that the thermal response is the slowest time scale in the system. Indeed, the slower time  $\tau_s$  we observe is much larger than either optical ( $\kappa_\alpha^{-1} \lesssim 3 \text{ ns}$ ) or mechanical ( $\gamma_\beta^{-1} \lesssim 20 \mu\text{s}$ ) lifetime, and we are not aware of any other similarly slow process occurring inside the device.

Finally, we use the measured value of  $\tau_0$  to estimate the thermal conductance. First, we need to calculate the heat capacity, for which we can use the known value for the specific heat  $c_V/T^3 = 8.3 \times 10^{-2} \text{ J}/(\text{mol} \cdot \text{K}^4)$  [20], which leads to the heat capacity per unit volume  $c_V/T^3 = 3 \times 10^3 \text{ J}/(\text{K}^4 \cdot \text{m}^3)$ . Next, we evaluate the volumes. The cavity has a diameter of  $d_{\text{cav}} = 133 \pm 5 \mu\text{m}$  and the length of  $l_{\text{cav}} = 70 \mu\text{m}$ , so its volume is  $V_{\text{cav}} = \frac{\pi}{4} d_{\text{cav}}^2 l_{\text{cav}} = (1.0 \pm 0.1) \times 10^{-12} \text{ m}^3$ . The sheaths have the same outer diameter  $d_{\text{cav}}$  (which is set by the inner diameter of the ferrule), the inner diameter  $d_{\text{sh}} = 125 \mu\text{m}$  and the length of  $l = 3 \text{ mm}$ ; this means that the combined volume of two sheaths  $V_{\text{sh}} = A_{\text{sh}} l = 2 \frac{\pi}{4} (d_{\text{cav}}^2 - d_{\text{sh}}^2) l = (3.5 \div 16) \times 10^{-12} \text{ m}^3$ . The large spread in the volume estimates is due to the uncertainty in the sheath thickness  $h_{\text{sh}} = (d_{\text{sh}} - d_{\text{cav}})/2 = (1.5 \div 6.5) \mu\text{m}$ . From the volume estimates

we obtain  $r_V = 0.06 \div 0.27$  and  $C_{\text{sh}}/T^3 = (1.0 \div 4.8) \times 10^{-8} \text{ J/K}^4$ . Using the experimental value for the time constant  $\tau_0 = 3.5 \times 10^{-4} \text{ s}$  we get  $K_{\text{sh}}/T^3 \equiv \epsilon = (2.5 \div 7.8) \times 10^{-5} \text{ W/K}^4$ .

We can assess the validity of this result using the theoretical expression for the thermal conductivity of a cylindrical channel[21]:

$$\kappa(T) = \frac{1}{3} c(T) v_{He} d_{\text{ch}} \frac{2-f}{f}, \quad (128)$$

which is applicable when the phonon mean free path is limited by the scattering at the channel boundaries. Here  $d_{\text{ch}}$  is the diameter of the channel, and  $f$  is the fraction of diffusive phonon scattering events at the channel walls. This equation can be rewritten as

$$\frac{2-f}{f} = \frac{3}{v_{He} d_{\text{ch}}} \frac{\kappa(T)}{c(T)} \quad (129)$$

We can apply this formula to the sheath by using equation 126 to express the ratio  $c/\kappa$ . With that, we find

$$\frac{2-f}{f} = \frac{3}{v_{He} d_{\text{ch}}} \frac{l^2}{\tau_0} \left( \frac{4}{\pi^2} + r_V \right) \quad (130)$$

If we approximate  $d_{\text{ch}}$  by twice the sheath thickness (to account for the much longer longitudinal scattering events)  $d_{\text{ch}} \approx 2h_{\text{sh}} = d_{\text{cav}} - d_{\text{sh}} = (3 \div 13) \mu\text{m}$ , we will find that the diffusive scattering fraction  $f$  is between 3% for the minimal sheath thickness of  $1.5 \mu\text{m}$  and 20% for the maximal sheath thickness of  $6.5 \mu\text{m}$ . These values appear reasonable for the optically smooth glass surfaces of the ferrule and the fiber and typical wavelength of thermal phonons  $\lambda_{\text{th}} = 2\pi \frac{\hbar v_{He}}{3k_B T} \gtrsim 10 \text{ nm}$  for  $T < 0.4 \text{ K}$ .

## SI D Cooperativity

In this section, we describe how the optomechanical cooperativity  $C$  and the single-photon cooperativity  $C_0$  are influenced by the cavity geometry and thermal conductance. Optomechanical cooperativity is defined in [22] as:

$$C = \frac{4(g^{\alpha,\beta})^2}{\kappa_\alpha \gamma_\beta} = \frac{4(g_0^{\alpha,\beta})^2 \bar{n}_\alpha}{\kappa_\alpha \gamma_\beta} = \bar{n}_\alpha C_0 \quad (131)$$

It is an important figure of merit in optomechanics, quantifying the efficiency of the system in exchanging photons and phonons [22]. Large cooperativity is necessary, e.g. for squeezing of light ( $C > n_{\text{th}}(1 + (2\omega_m/\kappa)^2)$ ) [23], efficient state transfer between optical and mechanical modes ( $C > n_{\text{th}}$ ) [24], and cooling the mechanical oscillator ( $n = \frac{n_{\text{th}} + C(\kappa/4\omega_m)^2}{C+1}$ ), where  $n$  is the lowest achievable phonon number [22]. While  $C$  is of interest, it is partially determined by the maximum number of photons that can be stored within the cavity. Since this number is typically limited by thermal constraints or optical nonlinearities, it is also useful to quantify device performance by defining the power-independent quantity  $C_0$  (single photon cooperativity).

### SI D.1 Single photon cooperativity

Here we describe how the single photon cooperativity  $C_0$  depends on the cavity geometry. As shown in equation 131, it depends on  $g_0^{\alpha,\beta}$ ,  $\kappa_\alpha$  and  $\gamma_\beta$ , all of which, in the case of helium confined in a Fabry-Perot cavity and neglecting any contributions to  $\gamma_\beta$  from the helium's internal loss, are approximately inversely proportional to cavity length. Therefore we do not expect single photon cooperativity to have a strong dependence on cavity length.

In this situation, for a cavity of length  $L$ , the optical linewidth  $\kappa_\alpha$  and mechanical linewidth  $\gamma_\beta$  are given by [25]:

$$\kappa_\alpha = \frac{c(1 - r_1^{(\text{opt})} r_2^{(\text{opt})})}{L r_1^{(\text{opt})} r_2^{(\text{opt})}} \quad (132)$$

and

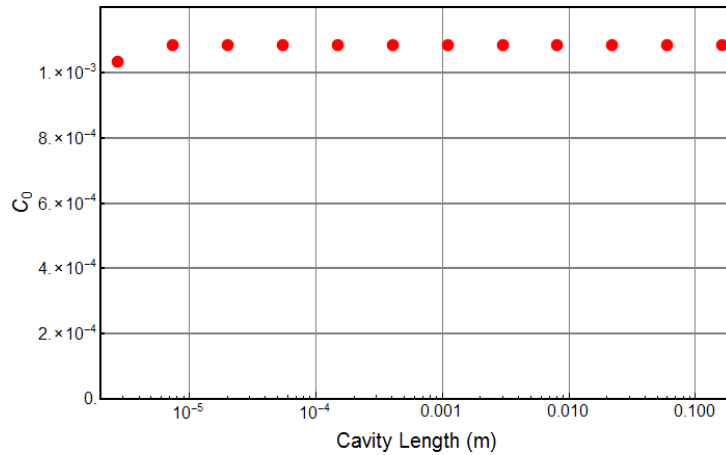
$$\gamma_\beta = \frac{v_{\text{He}}(1 - r_1^{(\text{ac})} r_2^{(\text{ac})})}{L r_1^{(\text{ac})} r_2^{(\text{ac})}} \quad (133)$$

The expression for the optomechanical coupling  $g_0^{\alpha,\beta}$  is given in the main text. It depends on the mode shape and size, which in turn depend on  $L$ ,  $R_1$ , and  $R_2$  (the radii of curvature of the two mirrors). As described in the main text, we use the paraxial approximation to obtain the profiles of both the acoustic and optical modes [25], and then find  $g_0^{\alpha,\beta}$  by numerical integration of Eq.1 in the main text. We find that  $g_0^{\alpha,\beta}$  is maximized for  $R_1, R_2 \simeq 0.54L$ . Intuitively this can be understood as follows. A cavity with  $R_1, R_2 = 0.5L$  (i.e. a spherical configuration) is unstable with a vanishing waist and diverging spot size at the mirrors. As  $R_1$  and  $R_2$  increase, the waist increases, while the mode diameter at the mirror surface decreases very rapidly. If  $R_1$  and  $R_2$  increase too much (i.e so as to approach a plane-plane configuration), the mode's transverse dimensions again diverge. The value  $R_1, R_2 \simeq 0.54L$  represents the optimal choice between these extremes.

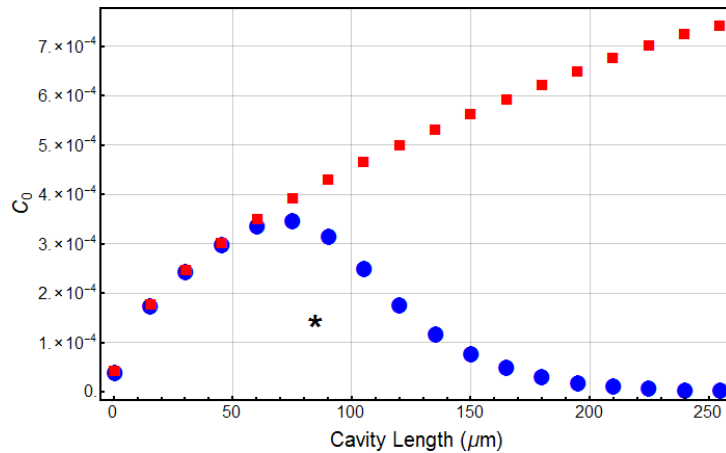
In the specific device described here, the values of the electric field reflectivities of the mirrors for 1550 nm light provided by the manufacturer are  $r_1^{(\text{opt})} = 0.99995$  and  $r_2^{(\text{opt})} = 0.999994$  [26], consistent with the calculations in section SI B and with the maximum measured finesse. The values  $r_1^{(\text{ac})} = 0.995$  and  $r_2^{(\text{ac})} = 0.996$  are the mirrors' amplitude reflectivities for the 315.7 MHz acoustic wave as calculated in section SI B, and confirmed by the measurements of the acoustic quality factor.

We first use equations 131, 132, 133 as well as the expression for  $g_0^{\alpha,\beta}$  to calculate  $C_0$  for cavities of various  $L$  and for  $R_1, R_2 = 0.54L$  assuming the mirrors are much larger than mode's transverse size (this assumption will be relaxed in what follows). For  $L > 5 \mu\text{m}$ ,  $C_0 \simeq 1.09 \times 10^{-3}$  and varies by less than 0.1%, so is practically independent of cavity length, confirming the qualitative reasoning above. The value  $C_0$  is plotted in figure 4 for varying cavity lengths.

The cavity used in this experiment does not have  $R_1 = R_2 = 0.54L$ , but rather has  $R_1 = 408 \mu\text{m}$ ,  $R_2 = 292 \mu\text{m}$  and  $L = 85.2 \mu\text{m}$ . These values were chosen as a compromise between satisfying the ideal relationship ( $R_1 = R_2 = 0.54L$ ), minimizing the potential impact of mirror misalignment, operating in the resolved sideband regime, maintaining a transverse mode smaller than the mirrors, and accomodating the range of  $R$  that can be achieved using the laser machining technique.  $C_0$  for such a cavity, calculated as before, and again neglecting the effect of the mirrors' finite size, is shown as a function of  $L$  in figure 5 using red squares.



**Figure 4:** Single photon cooperativity for different cavity lengths  $L$ , assuming mirrors with  $R_1, R_2 = 0.54L$



**Figure 5:** Single photon cooperativity for different cavity lengths for the mirrors used in the experiment.

However due to the fabrication process, the mirrors are not ideally shaped, but instead have a Gaussian profile with FWHM (Full Width at Half Maximum):  $d_1 = 36 \mu\text{m}$ ,  $d_2 = 41 \mu\text{m}$ . Only inside this FWHM does the mirror efficiently confine the cavity mode; this leads to clipping losses for longer cavities [1], diminishing the optical finesse. When the contributions of these clipping losses are included in  $\kappa_\alpha$  (using the treatment in [1]), the resulting  $C_0$  is shown with blue circles in figure 5.

The single photon cooperativity extracted from the experiment via direct measurement of  $\kappa_\alpha$ ,  $\gamma_\beta$  and the estimate of  $g_0^{\alpha,\beta}$  described in the main text is  $C_0 = 1.5 \times 10^{-4}$  and is marked with a black star in figure 5. The difference from the expected value of cooperativity (blue circles) is primarily due to the fact that optical finesse achieved in the device ( $\mathcal{F} = 2.56 \times 10^4$ ) differs from the optical finesse at this  $L$  extracted from the values of  $r_1^{(\text{opt})}$ ,  $r_2^{(\text{opt})}$ ,  $d_1$  and  $d_2$  ( $\mathcal{F} = 4.47 \times 10^4$ ), which could be a result of imperfect alignment, mirror surface contamination or deviations of the mirror shape.

## SI D.2 Heating limit for the optomechanical cooperativity.

As discussed in section SI C.1, heating of the helium inside the cavity causes an increase in the damping of the mechanical mode. This sets a practical limit on the incident optical power and, consequently, on the maximum multiphoton optomechanical cooperativity.

For a given heat load  $\Phi$  in steady state the temperature of the cavity is given by equation 113:

$$T_{\text{cav}}^4 = T_{\text{MC}}^4 + \frac{4\Phi}{\epsilon_l} l = T_{\text{MC}}^4 + \frac{4\Phi}{\epsilon}, \quad (134)$$

where  $\epsilon = \epsilon_l/l = \frac{K_{sh}}{T^3}$  is the coefficient for the temperature-dependent thermal conductance. This results in an internal damping rate (see equations 94-96)

$$\gamma_{\beta,\text{int}} = \frac{\omega_{\beta}}{Q_{\beta,\text{int}}} = \frac{\omega_{\beta}}{\chi} T_{\text{cav}}^4 = \frac{\omega_{\beta}}{\chi} \left( T_{\text{MC}}^4 + \frac{4\Phi}{\epsilon} \right) \quad (135)$$

The total damping is the of this intrinsic damping and the acoustic radiation set by the acoustic transmission at the helium-glass interface:

$$\gamma_{\beta} = \gamma_{\beta,\text{int}} + \gamma_{\beta,\text{rad}} = \frac{4\omega_{\beta}}{\chi\epsilon}\Phi + \frac{4\omega_{\beta}}{\chi}T_{\text{MC}}^4 + \gamma_{\beta,\text{rad}} \quad (136)$$

Thus,  $\gamma_{\beta}$  has three main components:

- (i) The intrinsic loss due to the optical heating

$$\gamma_{\beta,\Phi} = \frac{4\omega_{\beta}}{\chi\epsilon}\Phi \quad (137)$$

As noted in the main text, we can relate the heat load  $\Phi$  to the incident power  $P_{\text{inc}}$  and the circulating photon number  $\bar{n}_{\alpha}$ :

$$\Phi = \mu P_{\text{inc}} + \nu \hbar \omega_{\alpha} \kappa_{\alpha,\text{int}} \bar{n}_{\alpha} \quad (138)$$

This allows us to express the mechanical damping as

$$\gamma_{\beta,\Phi} = a_{\text{inc}} P_{\text{inc}} + a_{\text{circ}} \bar{n}_{\alpha} \quad (139)$$

with the coefficients  $a_{\text{inc}} = 4\mu\omega_{\beta}/(\chi\epsilon)$  and  $a_{\text{circ}} = (4\nu\hbar\omega_{\alpha}\kappa_{\alpha,\text{int}}\omega_{\beta})/(\chi\epsilon)$ . Using the experimentally determined values of  $\mu/\epsilon$  and  $\nu/\epsilon$  (provided in the main text) we find these to be  $a_{\text{inc}} = 2\pi \cdot (1.3 \pm 0.2) \cdot 10^8$  Hz/W and  $a_{\text{circ}} = 2\pi \cdot (2.1 \pm 0.2)$  Hz.

Both of these coefficients are inversely proportional to the thermal conductance coefficient  $\epsilon$ , meaning that improving the device thermalization enhances its power handling. In the present device the cavity is thermalized through a relatively long and narrow sheath of helium, as described in the main text, it should be possible to achieve a significant increase in thermal conductance by a small change the device construction. We can estimate this increase by using a standard result from kinetic theory, which is a generalization of equation 128:

$$\kappa = \frac{1}{3} c v_{He} \lambda, \quad (140)$$

where  $\lambda$  is the phonon mean free path. The corresponding thermal conductance for a 1D channel of cross-sectional area  $A$  and length  $l$  is

$$K = \frac{\kappa A}{l} = \frac{1}{3} \frac{c v_{He} \lambda A}{l} \quad (141)$$

For estimate we can assume a geometry where the cavity is formed between the two fiber faces as in the current device, but is not confined inside the alignment ferrule (e.g., each fiber is held in a separate ferrule with  $\sim 500 \mu\text{m}$  gap between the ferrule faces, as in [27]). For  $\sim 60 \mu\text{m}$  long cavity and  $\sim 125 \mu\text{m}$  fiber diameter we can approximate all relevant dimensions (including the mean free path) as  $100 \mu\text{m}$ :  $l \approx \lambda \approx 100 \mu\text{m}$ ,  $A \approx (100 \mu\text{m})^2$ . This results in the heat conductance  $K/T^3 = 2 \cdot 10^{-3} \text{ W/K}^4$ , which is to be compared to the sheath conductance  $K_{\text{sh}}/T^3 = (2.5 \div 7.8) \times 10^{-5} \text{ W/K}^4$ . Thus, it seems feasible to increase the heat conductance by a factor of 30. Assuming that the fraction of the optical losses dissipating into heat stays the same, we find that for such a device  $a_{\text{inc}} \approx 2\pi \cdot 4 \cdot 10^7 \text{ Hz/W}$  and  $a_{\text{circ}} = 2\pi \cdot 7 \cdot 10^{-2} \text{ Hz}$ .

- (ii) The second loss source is the intrinsic damping due to the finite mixing chamber temperature

$$\gamma_{\beta, \text{MC}} = \frac{4\omega_{\beta}}{\chi} T_{\text{MC}}^4 \quad (142)$$

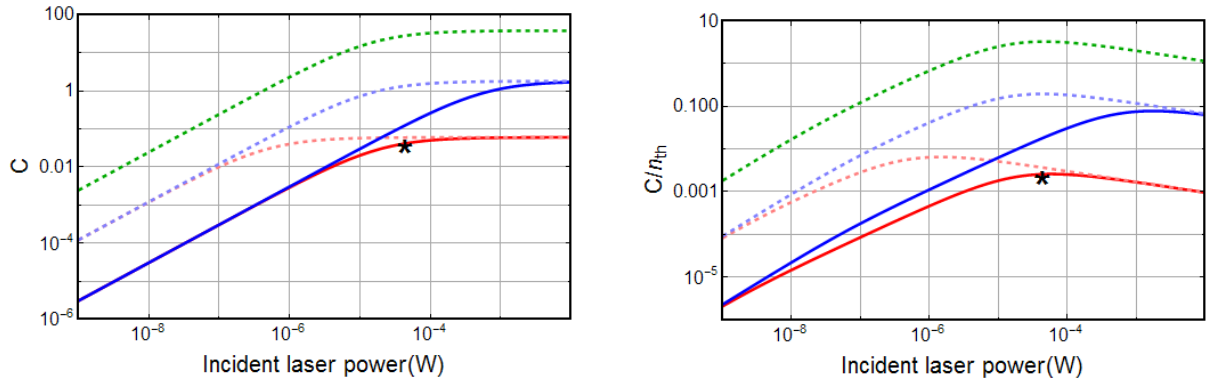
In the experiment the lowest achieved mixing chamber temperature is about 10 mK, and it consistently stayed below 50 mK unless a heater was used. This puts the associated damping below 20 Hz (corresponding to the quality factor  $> 1.5 \cdot 10^7$ ), which can be neglected compared to the effects of the cavity thermalization discussed in the previous paragraph.

- (iii) The last is the radiative loss associated with sound transmission through the helium/glass interface. This is described in detail in chapter SI B. Here we just note that this damping is independent of temperature, and that in the current device it limits the quality factor to  $79,000 \pm 5,000$  ( $\gamma_{\beta, \text{rad}} = 2\pi \cdot (4.0 \pm 0.3) \text{ kHz}$ ); implementing an acoustic DBR (described in section SI B.5) can raise the quality factor to  $(3.3 \pm 2.2) \cdot 10^6$  ( $\gamma_{\beta, \text{rad}} = 2\pi \cdot 100 \text{ Hz}$ ).

Expressions 131, 136 and 139 can be used to calculate the dependence of the multiphoton cooperativity on the incident optical power. In determining the circulating photon number we assume that 10% of the incident power is in the control beam detuned by  $\omega_{\beta}$  away from the cavity resonance, while the rest is in the optical local oscillator (OLO) detuned by about 1 GHz.

The results are shown in the left panel of figure 6. All of the lines demonstrate the same trend: for low powers the mechanical damping is dominated by the radiative losses and is independent of the incident power, so the cooperativity grows linearly with  $P_{\text{inc}}$ ; for high powers the mechanical linewidth is proportional to the incident power, and the cooperativity levels out. The theoretical calculations for the present device are denoted by a solid red line, with the black star denoting the maximal cooperativity obtained during Brownian motion measurements. The dashed red line corresponds to an increased radiative quality factor  $Q_{\text{rad}} = 3.3 \cdot 10^6$  (achieved by adding acoustic DBR, as discussed in section SI B.5), which improves the cooperativity at low power, but doesn't affect the saturation value. The solid blue line is the same as solid red, but it assumes a  $30\times$  increase in the thermal conductivity; this improves the high power behavior and maximal achievable cooperativity, but leaves the low power dependence the same. The dashed blue line includes both of these improvements, leading to a  $\sim 30$ -fold increase





**Figure 6:** Dependence of the multiphoton cooperativity  $C$  (left) and thermal multiphoton cooperativity  $C/n_{th}$  (right) on incident laser power. Line style denotes radiative mechanical losses  $\gamma_{\beta,rad}$ : solid lines correspond to  $Q_{\beta,rad} = 70,000$  (as for the current device), while dashed lines represent a device with  $Q_{\beta,rad} = 3.3 \cdot 10^6$ . The line color denotes the intrinsic temperature dependent mechanical damping  $\gamma_{\beta,\Phi}$ : red lines describe the current device, while the blue and the green lines suppose a factor of 30 improvement in thermal conductance. All the lines except for the green assume that 10% of the incident power is in the control beam detuned by 320 MHz from the cavity resonance; for the green line 100% of the incident power is in the control beam. In addition, the green line assumes that the optical linewidth is decreased from 69 MHz to 30 MHz (while keeping cavity length the same) and that the relative input coupling  $\kappa_{\alpha,in}/\kappa_{\alpha}$  is increased from 0.25 to 0.5. The black star denotes the maximum  $C \simeq 0.041$  and  $C/n_{th} \simeq 0.0025$  measured in the device. In those measurements the incident power was  $46 \mu\text{W}$ , mixing chamber temperature was 60 mK, total circulating photon number was  $\simeq 2000$  of which  $\simeq 1000$  photons were coming from the control beam. The control beam had  $\simeq 9 \%$  of the total incident power.

of cooperativity for all powers. Finally, the dashed green lines assumes additionally a decrease in the optical linewidth from 69 MHz to 30 MHz, an increase of the relative input coupling from 0.25 to 0.5, and the absence of the OLO, so that all of the incident power is concentrated in the control beam (which decreases the contribution to the thermal load associated with the OLO).

The right part of figure 6 shows another figure of merit, the thermal cooperativity, which is defined as a ratio of the multiphoton cooperativity to the equilibrium thermal phonon occupation. This quantity is important for quantifying the efficiency of quantum protocols, as it represents the ratio of the measurement strength to the thermal decoherence rate of the mechanical oscillator. In determining the phonon occupation, the equilibrium temperature of the mechanical oscillator is assumed to be equal to the helium temperature inside the cavity  $T_{cav}$  calculated using expression 113, which is consistent with the data from figure 4(c) in the main paper. For the optimized device (dashed green line) the thermal cooperativity exceeds unity for a wide range of powers, and can become as large as 5.

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